

b) Analytical study: quantitative dependence of dynamics on system parameters (8)

$$\frac{dp}{dt} = r p \left(1 - \frac{p}{P}\right) - \frac{\delta \cdot p}{1 + p/P_s}$$

→ make dimensionless:  $u = \frac{p}{P}$ ,  $\tau t = \tau$ ,  $\frac{\delta}{r} = \alpha$ ,  $\frac{P_s}{P} = \kappa$

$$\frac{du}{d\tau} = u(1-u) - \frac{\alpha u}{1+u/\kappa}$$

two dimensionless parameters:

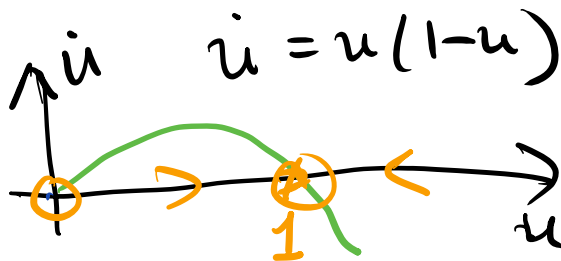
$\alpha = \frac{\delta}{r}$  large  $\alpha =$  high predation rate

$\kappa = P_s/P$  large  $\kappa =$  large predation capacity

Steady-state:

$$\frac{du}{d\tau} = 0 \rightarrow u^* = 0 \text{ or } 1 - u^* = \frac{\alpha}{1 + u^*/\kappa}$$

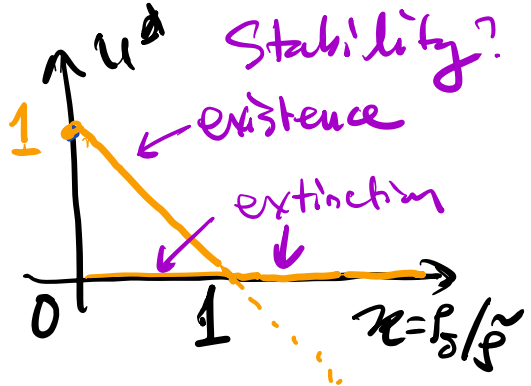
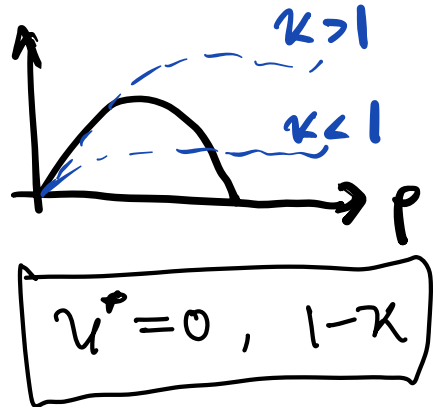
$\alpha = 0$ .  $u^* = 1$



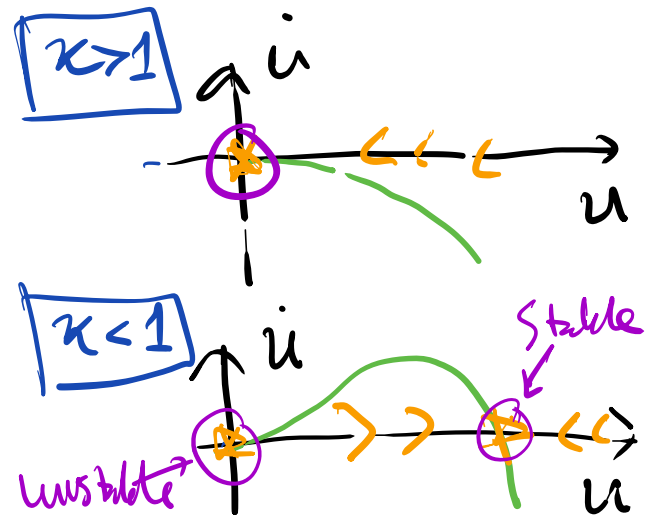
$\alpha > 0$   $(1-u^*) \cdot (\kappa + u^*) = \alpha \kappa$

$$(u^*)^2 + (\kappa - 1)u^* + (\alpha - 1)\kappa = 0$$

$\alpha = 1$   
borderline case with  $S=r$

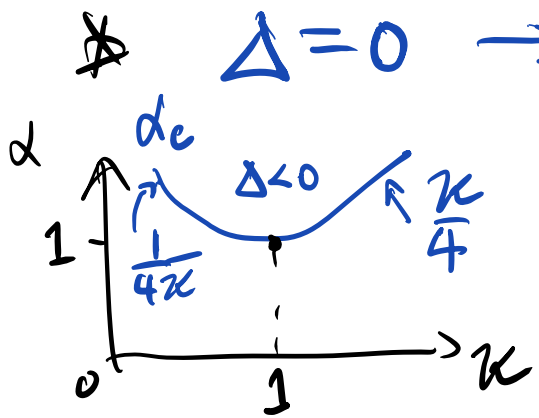


$$\begin{aligned} \dot{u} &= u(1-u) - \frac{u}{1+u/\kappa} \\ &= \frac{u}{1+u/\kappa} \cdot [(1-u)(1+u/\kappa) - 1] \\ &= \frac{u}{1+u/\kappa} \left[ \frac{u}{\kappa}(1-u) - u \right] \\ &= \frac{u^2}{u+\kappa} [1-\kappa-u] \end{aligned}$$



C) phase diagram: which phase is exhibited for what parameters ( $\alpha, \kappa$ )

$$u^* = \frac{1-\kappa}{2} \pm \sqrt{\underbrace{\left(\frac{\kappa-1}{2}\right)^2 - (\alpha-1)\kappa}_{\Delta \text{ (discriminant)}}} > 0$$



$\Delta = 0 \rightarrow \kappa^2 + 2\kappa + 1 = 4\alpha_c \kappa$

$4\alpha_c = \kappa + 2 + \frac{1}{\kappa}$

$4\alpha_c' = 1 - \frac{1}{\kappa^2} = 0$

min at  $\kappa=1, \alpha_c=1$  ( $4\alpha_c'' = \frac{2}{\kappa^3} > 0$ )

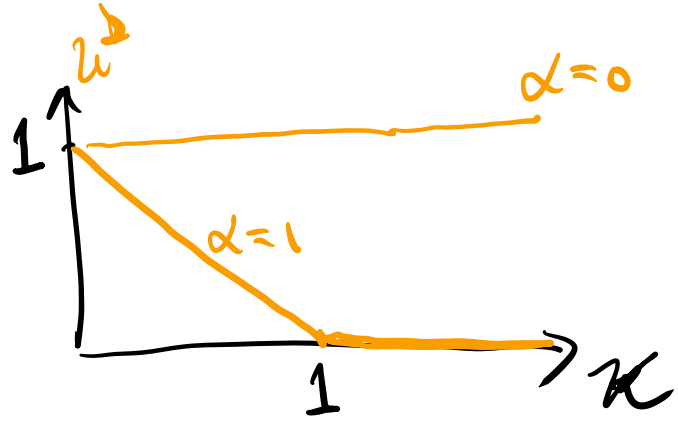
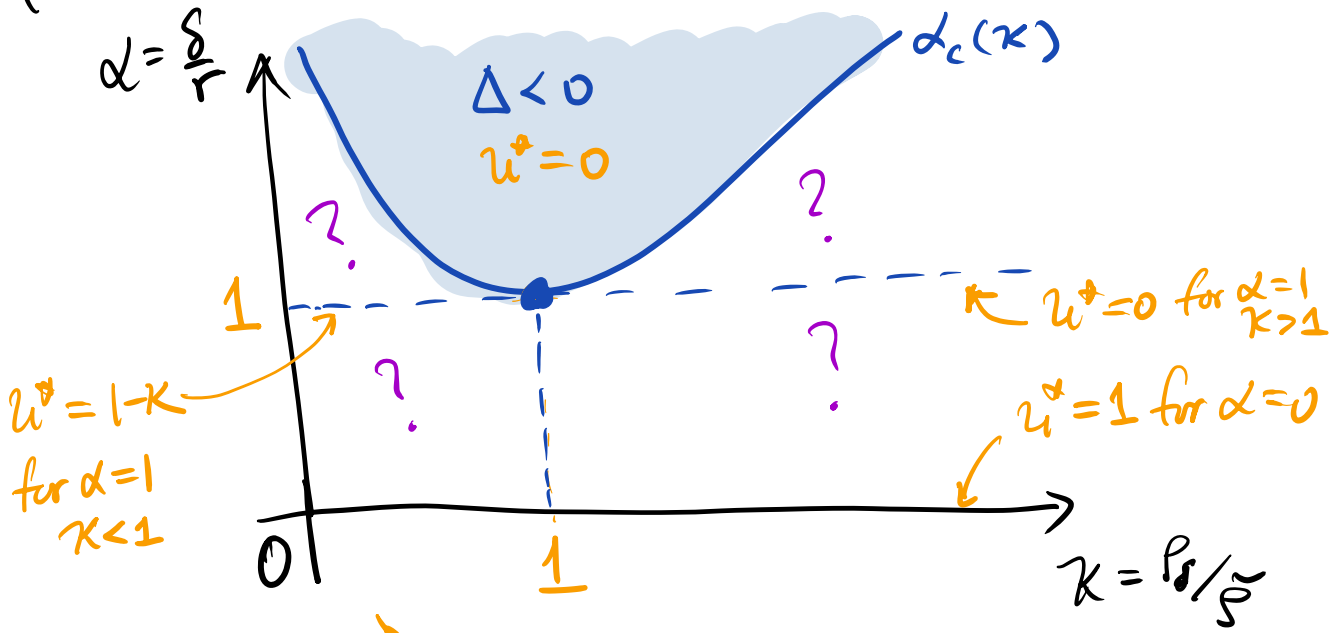
\* for  $\alpha > \alpha_c$ ,  $\Delta < 0$   $\rightarrow$  only sol'n is  $u^*=0$  (extinction!)

\* for  $\alpha < \alpha_c$ ;  $\Delta > 0$

→ one or two sol'n with  $u^* > 0$

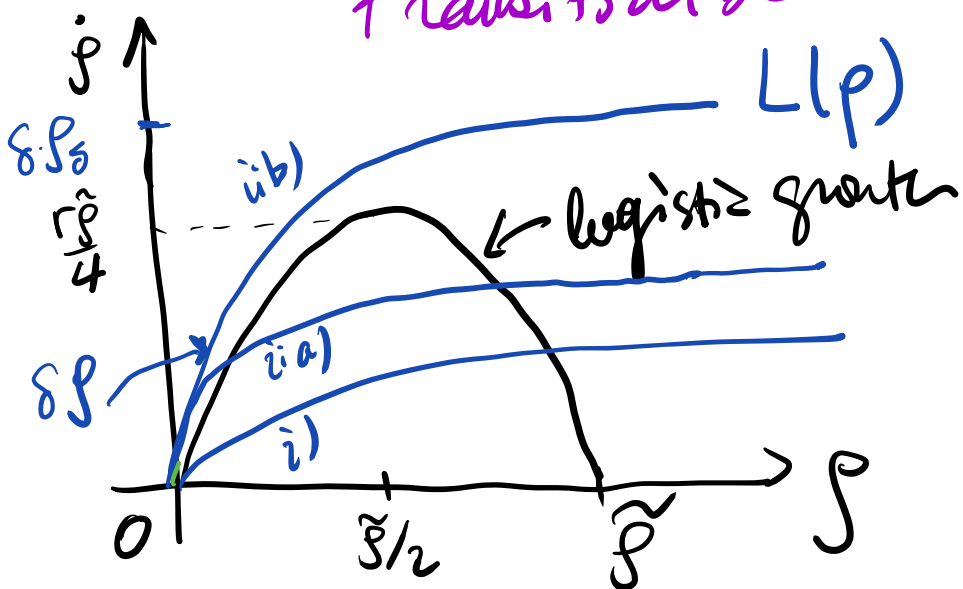
stable sol'n  
phase transition

phase diagram:



$u^*(\alpha, \kappa)$  for other values of  $\alpha$ ?

Recall 3 phases discussed at beginning  
transition between phases = "bifurcation"



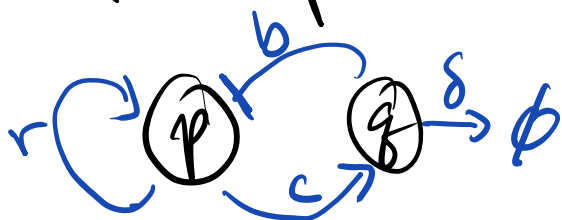
- i)  $\delta < r$  ( $\alpha < 1$ )
- ii)  $\delta > r$  ( $\alpha > 1$ )
  - ii a)  $\delta \cdot \beta_0 \leq r \tilde{\beta}/4$   
( $\alpha < \tilde{\kappa}/4$ )
  - ii b)  $\delta \cdot \beta_0 \geq r \tilde{\beta}/4$   
( $\alpha > \tilde{\kappa}/4$ )

### 3. Two-species interaction

(11)

#### a) Predator-Prey system

• two species:



Volterra (1926):

[Lotka (1920) introduced same eqn to describe chemical reactions]

prey (density  $P$ )  
predator (density  $Q$ )

$$\frac{dP}{dt} = rP - bPQ$$

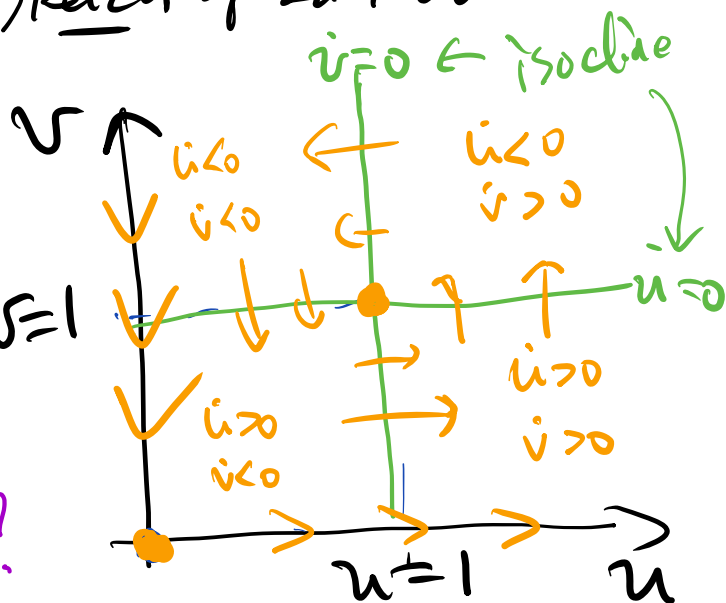
$$\frac{dQ}{dt} = cPQ - \delta Q$$

Lotka-Volterra Model

make dimensionless:  $u = P/\frac{\delta}{c}$ ,  $v = Q/\frac{r}{b}$ ,  $\tau = r \cdot t$ ,  $\alpha = \delta/r$

$$\begin{cases} \frac{du}{d\tau} = u(1-v) \\ \frac{dv}{d\tau} = \alpha v(u-1) \end{cases}$$

Sketch of 2d flow



Fixed pt:  $(\vec{u}, \vec{v}) = (0,0), (1,1)$

→ dynamics around  $(1,1)$ :  
damped or unstable spiral?

let  $\begin{cases} u = 1+x \\ v = 1+y \end{cases} \rightarrow \begin{cases} \frac{dx}{d\tau} = -y \\ \frac{dy}{d\tau} = \alpha x \end{cases}$  or  $\frac{d^2 x}{d\tau^2} = -\frac{dy}{d\tau} = -\alpha x$

$$\Rightarrow \begin{cases} x(z) = x_0 e^{\pm i k z} \\ y(z) = y_0 e^{\pm i k z} \end{cases}$$

oscillatory sol'n; but depends on init cond ??

full solution:  $\frac{du/dz}{dv/dz} = \frac{du}{dv} = \frac{u(1-v)}{\alpha v(u-1)}$

$$\alpha \frac{du}{u} (u-1) = \frac{dv}{v} (1-v)$$

$$\alpha u - \ln u^\alpha = \ln v - v + H$$

← const.

$$H(u,v) = \alpha u + v - \alpha \ln u - \ln v$$

- conserved quantity!

at  $u=1, v=1, H(1,1) = 1 + \alpha \equiv H_0$

→  $H(u,v)$  has global min at  $u=1, v=1$  (with value  $H_0 = 1 + \alpha$ )

$$\left[ \begin{array}{l} \frac{\partial H}{\partial u} = \alpha - \frac{\alpha}{u} = 0 \text{ at } u^* = 1; \quad \frac{\partial^2 H}{\partial u^2} = \frac{\alpha}{u^2} > 0 \\ \frac{\partial H}{\partial v} = 1 - \frac{1}{v} = 0 \text{ at } v^* = 1; \quad \frac{\partial^2 H}{\partial v^2} = \frac{1}{v^2} > 0 \end{array} \right]$$

trajectory of orbits:

-  $H \gtrsim H_0$ : let  $u = 1+x, v = 1+y$ .

$$\alpha + \alpha x + 1 + y - \ln(1+x)^\alpha - \ln(1+y) = H$$

$$(\alpha x + y) - \alpha \left(x - \frac{x^2}{2}\right) - \left(y - \frac{y^2}{2}\right) = H - H_0$$

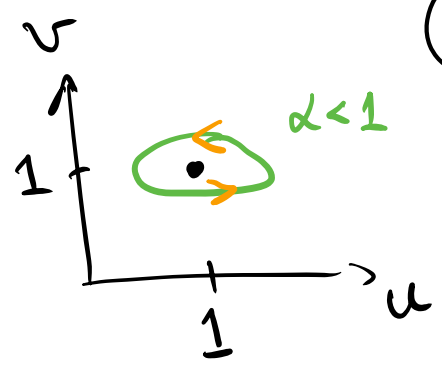
$\rightarrow \alpha \frac{x^2}{2} + \frac{y^2}{2} = H - H_0$  (ellipse)

$y=0 \quad x = \pm \sqrt{\frac{2}{\alpha}(H-H_0)}$

long-axis along x if  $\alpha < 1$

(Corresponding to  $\delta < r$ )

$\uparrow$  prey replication rate  
 $\uparrow$  predator death rate



-  $H \gg H_0$ : look at  $\alpha u + v - \alpha \ln u - \ln v = H$

for large  $u, v$ , can neglect  $\ln u, \ln v$

$\rightarrow \alpha u + v \approx H$

• breaks down when  $u, v \rightarrow 0$

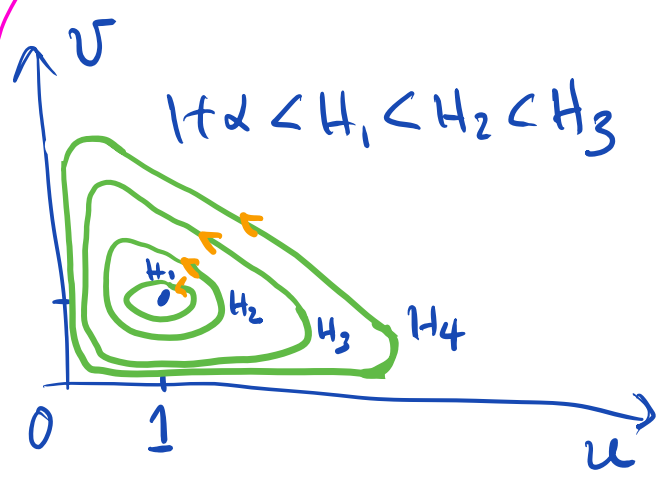
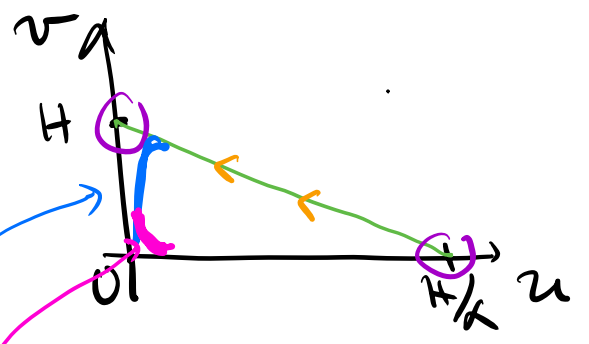
Consider  $v \approx H, u \rightarrow 0$ .

here  $v \approx H + \alpha \ln u$

• for both  $u, v \ll 1$

$-H = \alpha \ln u + \ln v = \ln v \cdot u^\alpha$

$v = u^{-\alpha} e^{-H}$



Overall lesson: conserved quantity  $\rightarrow$  periodic orbit.

but solution completely dependant on init cond.

b) break conserved quantity  
 e.g. include logistic growth of prey.

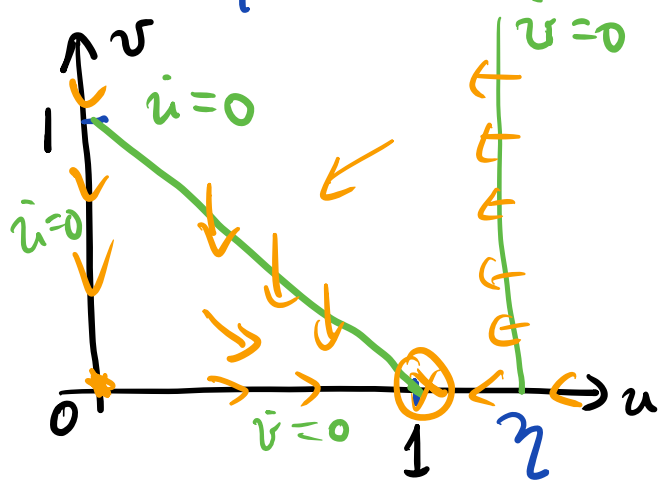
$$\begin{cases} \frac{dp}{dt} = r p (1 - p/\tilde{p}) - b p q \\ \frac{dq}{dt} = c p q - \delta q \end{cases}$$

ratio of death rate to max predator growth rate

dimensionless:  $u = p/\tilde{p}$ ,  $v = q \frac{b}{r}$ ,  $\tau = r \cdot t$ ,  $\alpha = \delta/r$ ,  $\eta = \frac{\delta}{\tilde{p}c}$

$$\begin{cases} \frac{du}{d\tau} = u(1-u-v) \\ \frac{dv}{d\tau} = \alpha v \left( \frac{u}{\eta} - 1 \right) \end{cases} \quad \begin{aligned} \dot{u} = 0 &: u = 0 \text{ or } u + v = 1 \\ \dot{v} = 0 &: v = 0 \text{ or } u = \eta \end{aligned}$$

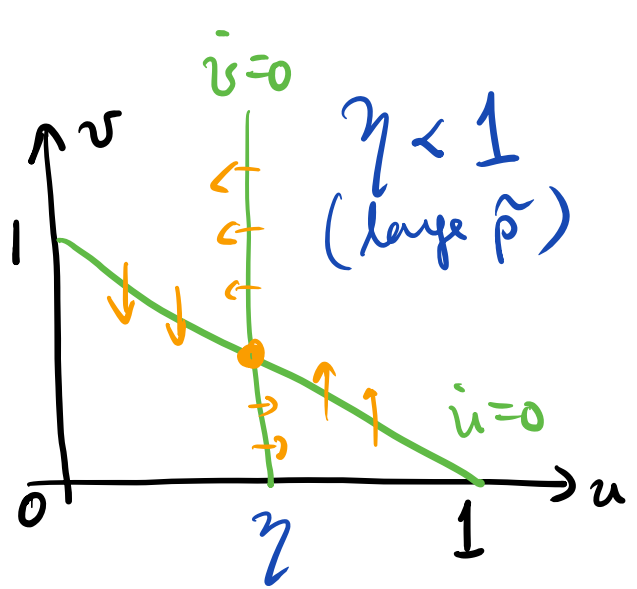
$\eta > 1$  (a small  $\tilde{p}$ : small carrying capacity for prey)



predator extinct  
 prey  $\rightarrow$  carrying capacity

$\Rightarrow$  Small carrying capacity for prey leads to collapse of predators

(c.f. dinosaur)



Check for stability and oscillation

$$\begin{aligned} u^* &= \eta, \quad v^* = 1 - u^* = 1 - \eta \\ u &= \eta + x, \quad v = 1 - \eta + y \end{aligned}$$

for small  $x, y$

$$\begin{cases} \frac{dx}{d\tau} = -\eta \cdot (x + y) \\ \frac{dy}{d\tau} = \alpha(1-\eta) \cdot \frac{x}{\eta} \end{cases}$$